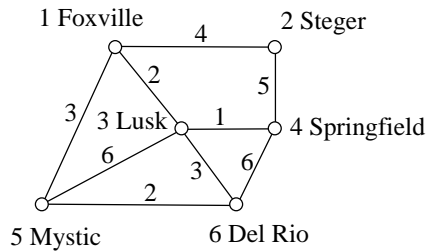


# Minimal Spanning Tree (1/11)

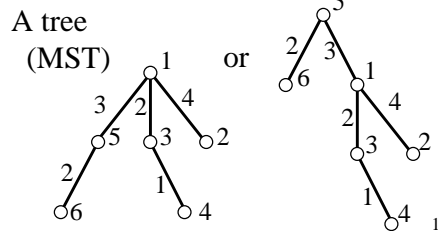
✦ JohnsonBaugh's *Algorithms*, Section 7.2 (page 275) find Minimal Spanning Tree (MST) with **Kruskal's algorithm**:

**Six cities**



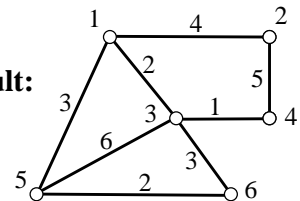
We want to construct a set of interconnecting roads such that one can reach any city from any starting city and the **total construction costs are minimized**.

The estimated costs for some pairs of cities are as labeled.



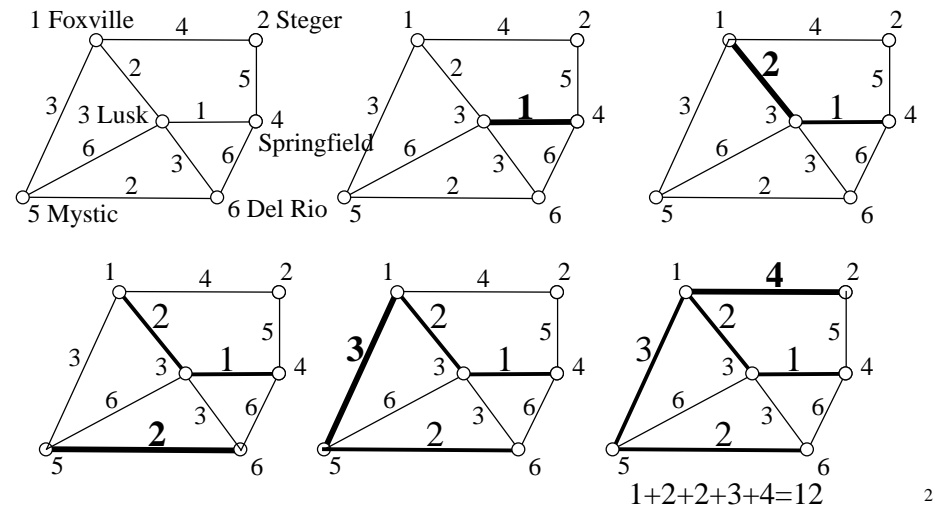
**Result:**

Best



# Kruskal's MST (2/11)

✦ **Kruskal's algorithm**



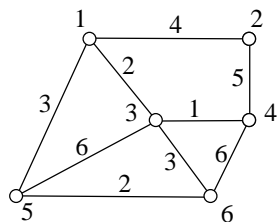
# Kruskal's MST (3/11)

Array of edges:

(1,2,4), (1,3,2), (1,5,3), (2,4,5), (3,4,1), (3,5,6),  
(3,6,3), (4,6,6), (5,6,2)

Sorted array of edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)



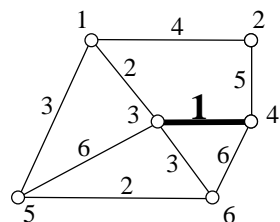
MST: {}

{  
 1 find the edge with minimal weight  
 2 add to MST if the edge does not form a cycle

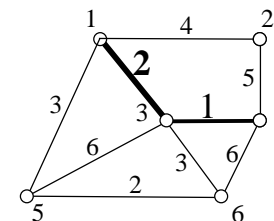
MST: {3,4}

Remaining edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)



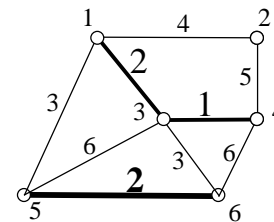
# Kruskal's MST (4/11)



MST: {1,3,4}

Remaining edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)

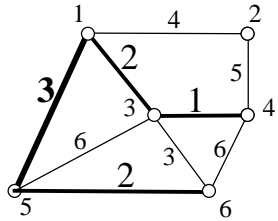


MST: {1,3,4}, {5,6}

Remaining edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)

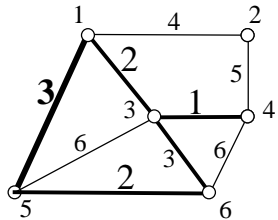
## Kruskal's MST (5/11)



MST: {1,3,4,5,6}

Remaining edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)



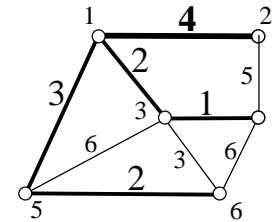
MST: {1,3,4,5,6}

Remaining edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)

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## Kruskal's MST (6/11)



MST: {1,2,3,4,5,6}

Remaining edges:

(3,4,1), (1,3,2), (5,6,2), (1,5,3), (3,6,3), (1,2,4),  
(2,4,5), (3,5,6), (4,6,6)

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## Kruskal's MST (7/11)

Array of edges: (vertex1, vertex2, weight)

(1,2,4), (1,3,2), (1,5,3), (2,4,5), (3,4,1), (3,5,6), (3,6,3), (4,6,6), (5,6,2)

❖ Implementation ❶: 2-dimensional arrays (or parallel arrays)

```
int edges[][3] = { {1,2,4}, {1,3,2}, {1,5,3}, {2,4,5}, {3,4,1},
                  {3,5,6}, {3,6,3}, {4,6,6}, {5,6,2} };
int nEdges = sizeof(edges) / sizeof(int[3]);
```

❖ Implementation ❷: array of struct

```
struct Edge {
    int vertex1, vertex2, weight;
};
struct Edge edges[] = { {1,2,4}, {1,3,2}, {1,5,3}, {2,4,5}, {3,4,1},
                       {3,5,6}, {3,6,3}, {4,6,6}, {5,6,2} };
int nEdges = sizeof(edges) / sizeof(struct Edge);
```

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## Kruskal's MST (8/11)

Sorted array of edges:

(3,4,1), (5,6,2), (1,3,2), (1,5,3), (3,6,3), (1,2,4), (2,4,5), (3,5,6), (4,6,6)

```
❖ Simple selection sort on 2-dimensional arrays (slightly different results from previous slides)
01 void selectionSort(int edges[][3], int nEdges) {
02     int i, max;
03     for (i=0; i<nEdges-1; i++) {
04         max = findMaximum(edges, nEdges-i);
05         swap(edges[nEdges-i-1], edges[max]);
06     }
07 }
void swap(int a[3], int b[3]) {
08     int tmp, i;
09     for (i=0; i<3; i++) {
10         tmp = a[i];
11         a[i] = b[i];
12         b[i] = tmp;
13     }
14 }
09 int findMaximum(int edges[][3], int nEdges) {
10     int i, max=nEdges-1;
11     for (i=nEdges-2; i>=0; i--)
12         if (edges[i][2] > edges[max][2])
13             max = i;
14     return max;
15 }
```

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## Kruskal's MST (9/11)

Sorted array of edges:

(3,4,1),(5,6,2),(1,3,2),(1,5,3),(3,6,3),(1,2,4),(2,4,5),(3,5,6),(4,6,6)

✧ stdlib qsort on array of structs

```
#include <stdlib.h>

int compare(void *arg1, void *arg2) {
    return ((struct Edge *)arg1->weight - ((struct Edge *)arg2->weight);
}

qsort(edgelist, nEdges, sizeof(struct Edge), compare);
```

Sorted array of edges:

(3,4,1),(1,3,2),(5,6,2),(1,5,3),(3,6,3),(1,2,4),(2,4,5),(3,5,6),(4,6,6)

✧ requires a stable sorting algorithm: e.g. bubble, bucket, insertion, counting, merge, radix, ...

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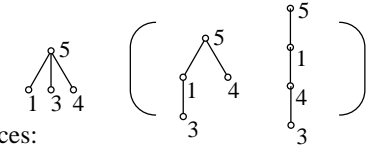
## Kruskal's MST (10/11)

MST: {} → {3,4} → {1,3,4} → {1,3,4}, {5,6} → {1,3,4,5,6} → {1,2,3,4,5,6}

✧ Require "set processing" tools: union, comparison

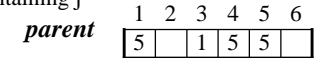
✧ Specially, these are disjoint sets (Section 3.6 of JohnsonBaugh, pp.150):

\* Set members are held in the same tree, root node represents the set



\* use an array *parent* to implement the set membership and provide three interfaces:

- ✧ **makeset**(i): construct the set {i}
- ✧ **findset**(i): returns the representative node of the set
- ✧ **union**(i,j): joins the set containing i and the set containing j



```
void makeset(int i, int nNodes, int parent[]) {
    if ((i<0)||i>=nNodes) return;
    parent[i] = i;
}
```

```
int findset(int i, int nNodes, int parent[]) {
    if ((i<0)||i>=nNodes) return -1;
    while (i != parent[i])
        i = parent[i];
    return i;
}
```

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## Kruskal's MST (11/11)

```
void mergetrees(int i, int j, int nNodes, int parent[]) {
    if (((i<0)||i>=nNodes) || ((j<0)||j>=nNodes)) return;
    parent[i] = j;
}

void union(int i, int j, int nNodes, int parent[]) {
    if (((i<0)||i>=nNodes) || ((j<0)||j>=nNodes)) return;
    mergetrees(findset(i, nNodes, parent), findset(j, nNodes, parent), nNodes, parent);
}
```

- ❶ find the edge with minimal weight
- ❷ add to MST if the edge does not form a cycle

```
for (iEdge=0; treeSize=0; treeSize<nNodes; iEdge++) {
    if (findset(edgelist[iEdge][0], nNodes, nodeSet) !=
        findset(edgelist[iEdge][1], nNodes, nodeSet)) {
        totalWeight = totalWeight + edgelist[iEdge][2]; treeSize++;
        union(edgelist[iEdge][0], edgelist[iEdge][1], nNodes, nodeSet);
    }
}
```

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